

Dear Reviewers,

in reply to your comments we have added a brief description of trocar placement and Da Vinci Xi docking (page 5 of the manuscript, lines from 21 to 28); we have also provided a figure representing the position of the robot and the ports (figure 3).

The signed Conflict-of-Interest Disclosure Form and Copyright License Agreement have been added.

The original figure documents have been prepared and arranged using PowerPoint.

We have put the reference's number in the square bracket and made it be superscript.

We have provided the PubMed numbers and DOI citation numbers to the reference list and listed all authors of the references.

Best regards

On behalf of all authors

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