



All

Images

Videos

翻译成中文

关闭取词

15,300 Results

Any time ▼

Towards more effective robotic gait training for stroke ...

<https://www.ncbi.nlm.nih.gov/pmc/articles/PMC3481425>

Robot-driven **gait** therapy can provide assistance to patients during training and offers a number of advantages over other forms of therapy. ... The Ambulation-Assisting Robotic Tool for Human Rehabilitation (ARTHuR) is an **end-effector** system where **leg** movements are controlled via ... Brouwer B. **Muscle strengthening** and physical conditioning to ...

Cited by: 163

Author: Andrew Pennycott, Andrew Pennycott, D...

Publish Year: 2012

Innovative gait robot for the repetitive practice of floor ...

<https://jneuroengrehab.biomedcentral.com/articles/10.1186/1743-0003-7-30> ▼

Jun 28, 2010 · Stair climbing up and down is an essential part of everyday's mobility. To enable wheelchair-dependent patients the repetitive practice of this task, a novel **gait robot**, G-EO-Systems (EO, Lat: I walk), based on the **end-effector** principle, has been designed. The trajectories of the foot plates are freely programmable enabling not only the practice of simulated floor walking but also stair ...

Published in: [Journal of Neuroengineering and Rehabilitation](#) · 2010Authors: [Stefan Hesse](#) · [Andreas Waldner](#) · [Christopher Tomelleri](#)Affiliation: [Medical Park](#)About: [Robotics](#) · [Brain ischemia](#) · [Stair climbing](#) · [Physical medicine and rehabilitation](#) · [Lowe...](#)

Use of the robot assisted gait therapy in rehabilitation ...

https://www.researchgate.net/publication/224867329_Use_of_the_robot_assisted_gait...

use of the **robot** assisted **gait** therapy in **rehabilit ation of p atients with str oke** and spinal cord injury
sale Vol. 48 - No. 1 EUROPEAN JOURNAL OF PHYSICAL AND REHABILITA TION MEDICINE 119 32.

Innovative gait robot for the repetitive practice of floor ...

<https://www.ncbi.nlm.nih.gov/pmc/articles/PMC2914004>

Stair climbing up and down is an essential part of everyday's mobility. To enable wheelchair-dependent patients the repetitive practice of this task, a novel **gait robot**, G-EO-Systems (EO, Lat: I walk), based on the **end-effector** principle, has been designed. The trajectories of the foot plates are ...

Cited by: 156

Author: Stefan Hesse, Andreas Waldner, Christop...

Publish Year: 2010

Robot-assisted gait training for stroke patients: current ...

<https://www.dovepress.com/robot-assisted-gait-training-for-stroke-patients-current...> ▼

Name of Journal: *World Journal of Clinical Cases*

Manuscript NO: 48556

Manuscript Type: ORIGINAL ARTICLE

Prospective Study

Immediate muscle strengthening by an end-effector type gait robot with reduced real-time use of leg muscles: A case series and review of literature

Hwang CH. Efficient strengthening with a robot

Chang Ho Hwang

Abstract

BACKGROUND

Match Overview

There are no matching sources for this report.



All

Images

Videos

翻译成中文

关闭取词

5,660 Results

Any time ▾

Towards more effective robotic gait training for stroke ...

<https://www.ncbi.nlm.nih.gov/pmc/articles/PMC3481425>

Robot-driven gait therapy can provide assistance to patients during training and offers a number of advantages over other forms of therapy. ... The Ambulation-Assisting Robotic Tool for Human Rehabilitation (ARTHUR) is an **end-effector** system where **leg** movements are controlled via ... Brouwer B. **Muscle strengthening** and physical conditioning to ...

Cited by: 165

Author: Andrew Pennycott, Andrew Pennycott, D...

Publish Year: 2012

Innovative gait robot for the repetitive practice of floor ...

<https://jneuroengrehab.biomedcentral.com/articles/10.1186/1743-0003-7-30> ▾

Jun 28, 2010 · Stair climbing up and down is an essential part of everyday's mobility. To enable wheelchair-dependent patients the repetitive practice of this task, a novel **gait robot**, G-EO-Systems (EO, Lat: I walk), based on the **end-effector** principle, has been designed. The trajectories of the foot plates are freely programmable enabling not only the practice of simulated floor walking but also stair ...

Published in: [Journal of Neuroengineering and Rehabilitation](#) · 2010

Authors: [Stefan Hesse](#) · [Andreas Waldner](#) · [Christopher Tomelleri](#)

Affiliation: [Medical Park](#)

About: [Brain ischemia](#) · [Neurology](#) · [Lower limb muscle](#) · [Gait](#) · [Robotics](#) · [Stair climbing](#)

Innovative gait robot for the repetitive practice of floor ...

<https://www.ncbi.nlm.nih.gov/pmc/articles/PMC2914004>

Stair climbing up and down is an essential part of everyday's mobility. To enable wheelchair-dependent patients the repetitive practice of this task, a novel **gait robot**, G-EO-Systems (EO, Lat: I walk), based on the **end-effector** principle, has been designed. The trajectories of the foot plates are ...

Cited by: 166

Author: Stefan Hesse, Andreas Waldner, Christop...

Publish Year: 2010

Electromechanical-assisted gait training after stroke: A ...

https://www.researchgate.net/publication/221874252_Electromechanical-assisted_gait...

PDF | Although electromechanical-assisted gait training after stroke seems to be effective, in the absence of a direct comparison between electromechanical devices it is not clear which device may ...